

# Descending, lifting or smoothing: Secrets of robust cost optimization

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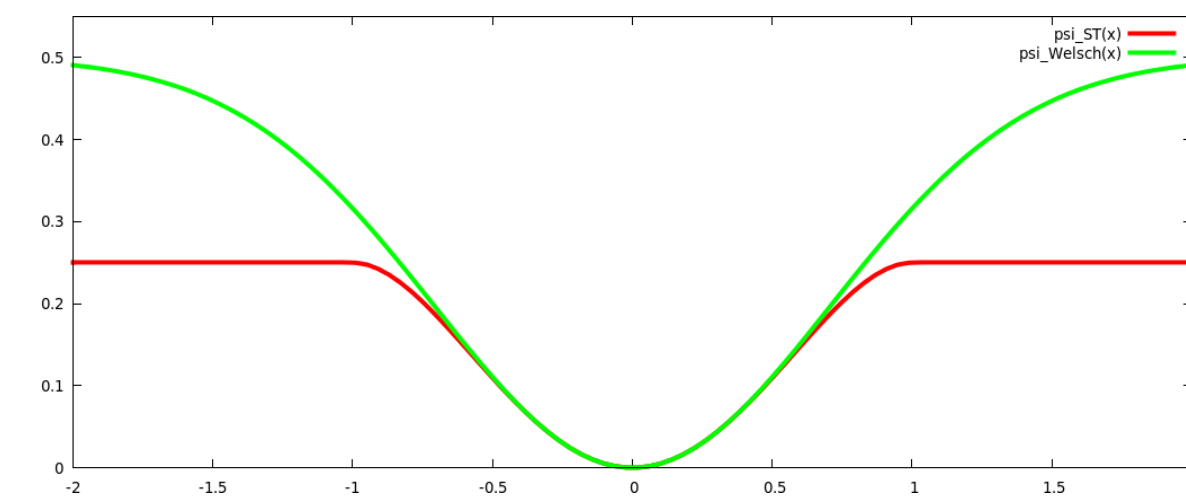
## 1) Introduction

### Problem statement

Minimize a cost function involving robust data terms

$$\min_{\theta} \Psi(\theta) \quad \text{with} \quad \Psi(\theta) = \sum_i \psi(\|\mathbf{f}_i(\theta)\|)$$

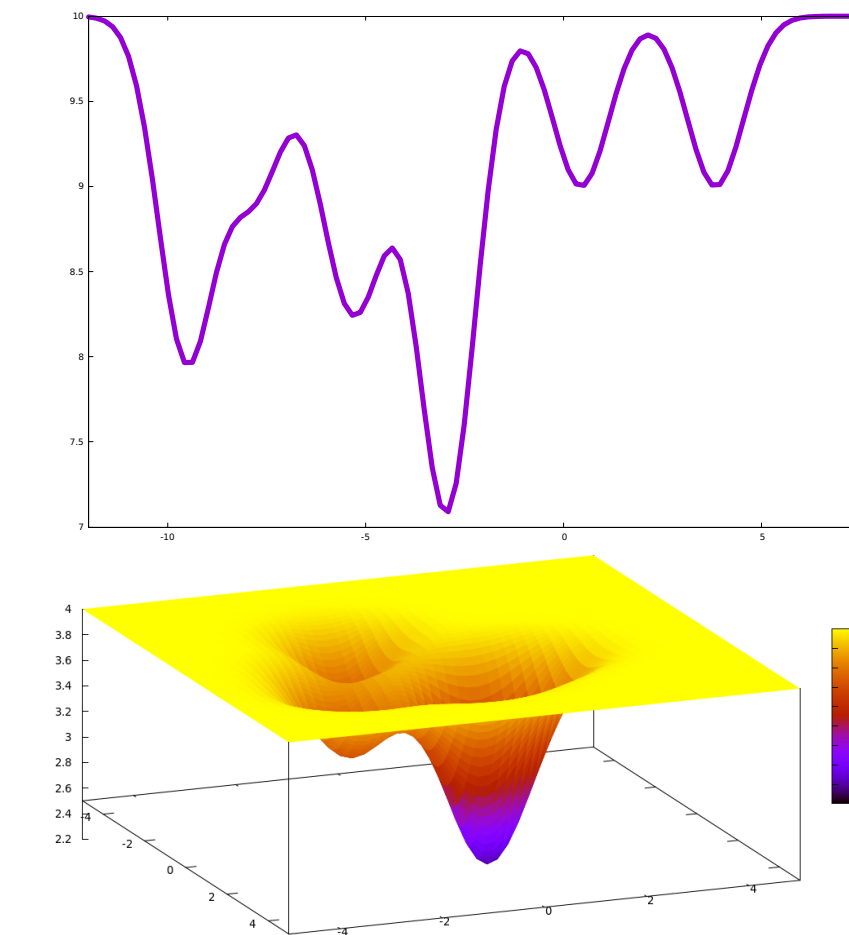
where  $\mathbf{f}_i(\theta) : \mathbb{R}^p \rightarrow \mathbb{R}^d$  and  $\psi(\cdot)$  is a robust kernel function.



### Challenges

- large number of local minima
- large number of parameters to estimate

How to obtain an efficient algorithm able to escape poor local minima?



### Take-home message:

	Direct methods	Lifting methods	Graduated optimization
Speed of convergence	++	+	-
Ability to escape local minima	-	+	++

## 2) Direct methods

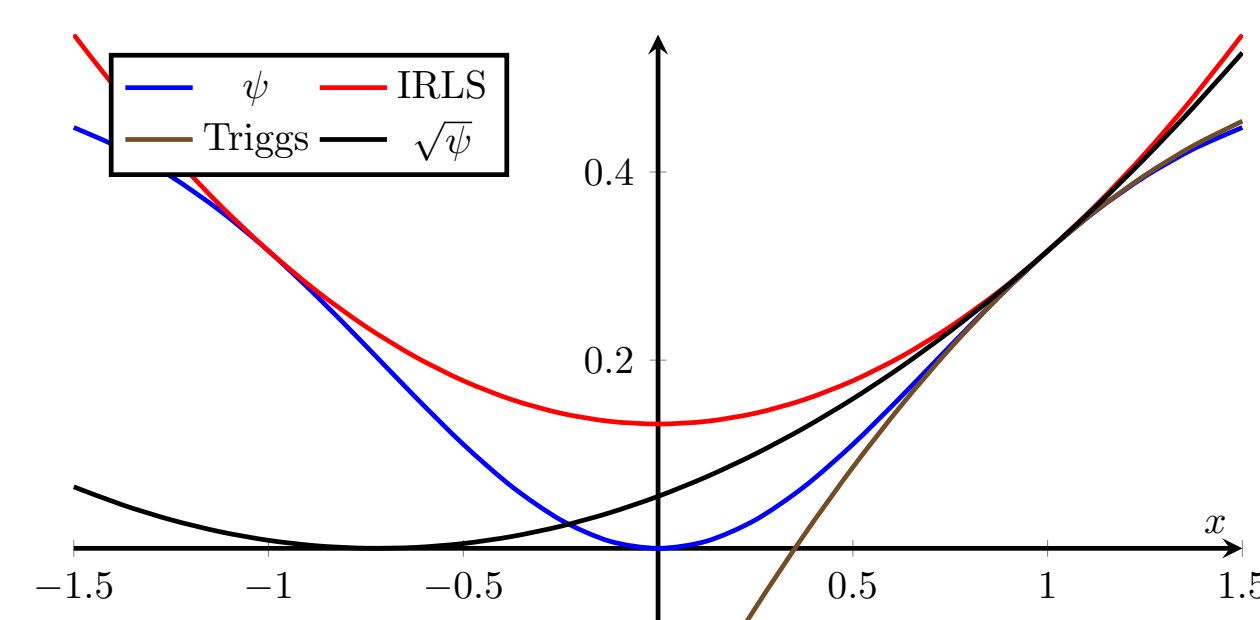
Minimize  $\Psi(\theta)$  directly using an NLLS solver:

1. First order approximation of  $\mathbf{f}_i(\theta)$  at  $\theta = \bar{\theta}$ :

$$\mathbf{f}_i(\bar{\theta} + \Delta\theta) \approx \bar{\mathbf{f}}_i + \mathbf{J}_i \Delta\theta$$

2. Approximate  $\psi(\|\bar{\mathbf{f}}_i + \mathbf{J}_i \Delta\theta\|)$  with a quadratic model  $\check{\psi}$  s.t.

$$\psi(\|\bar{\mathbf{f}}_i\|) = \check{\psi}(\|\bar{\mathbf{f}}_i\|)$$

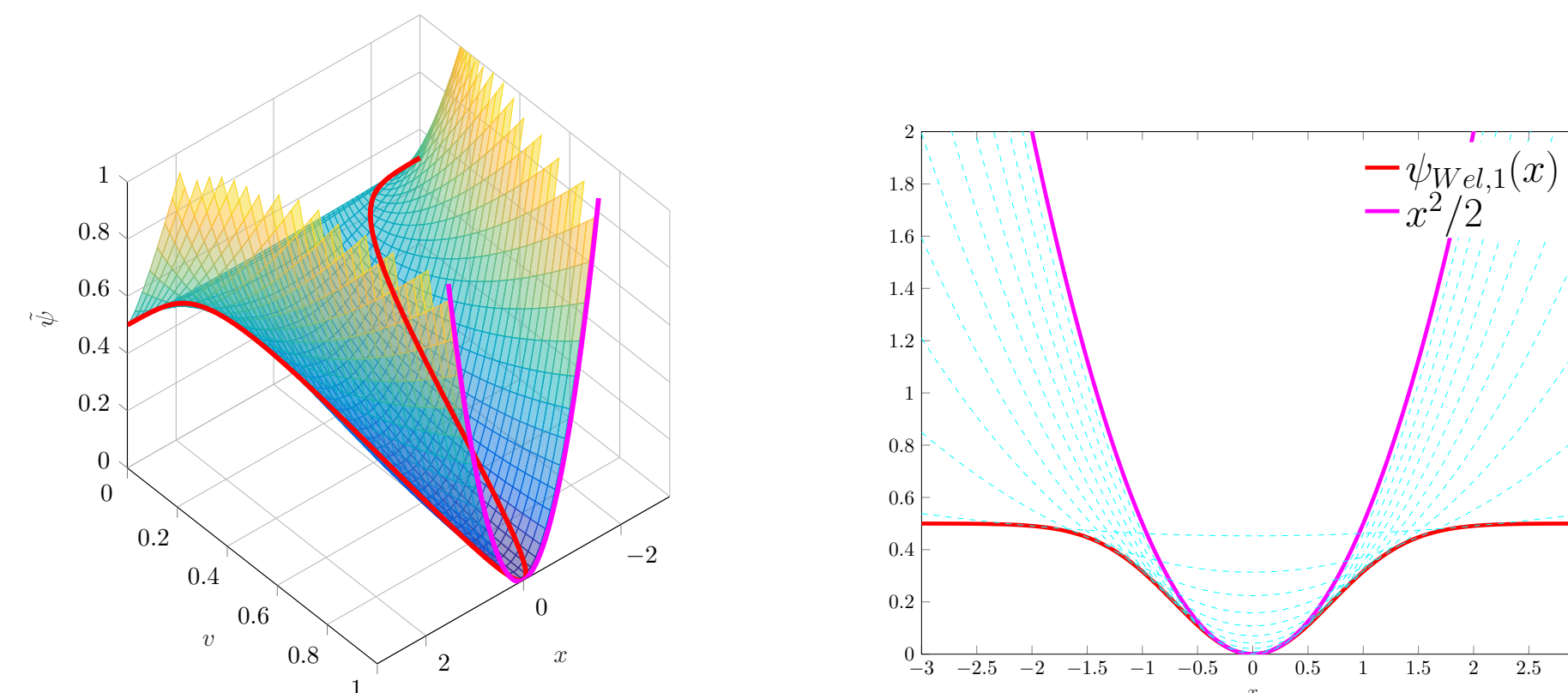


Quadratic surrogate models used by different direct approaches at  $\bar{\theta} = 1$  (the x-axis corresponds to  $\theta = \bar{\theta} + \Delta\theta$ )

**Our contribution** The underlying quadratic models are very different and the IRLS model has desirable properties.

## 3) Half-quadratic lifting-based methods

1. Use a *quadratic basis kernel* to lift  $\psi(x)$ : 
$$\psi(x) = \min_{v \in [0,1]} \frac{v}{2} x^2 + \gamma(v)$$



Half-quadratic lifting [1] of  $\psi_{\text{Wel},1}(x)$ ,

2. Rewrite  $\Psi(\theta)$  to obtain an NLLS problem:

$$\min_{\theta} \sum_i \psi(\|\mathbf{f}_i(\theta)\|) = \min_{\theta, \{v_i\}_i} \sum_i \left\| \frac{\sqrt{v_i}}{\sqrt{2}} \mathbf{f}_i(\theta) \right\|^2$$

**Our contribution** A convexified Newton approximation to replace the Gauss-Newton approximation [1] in the NLLS solver.

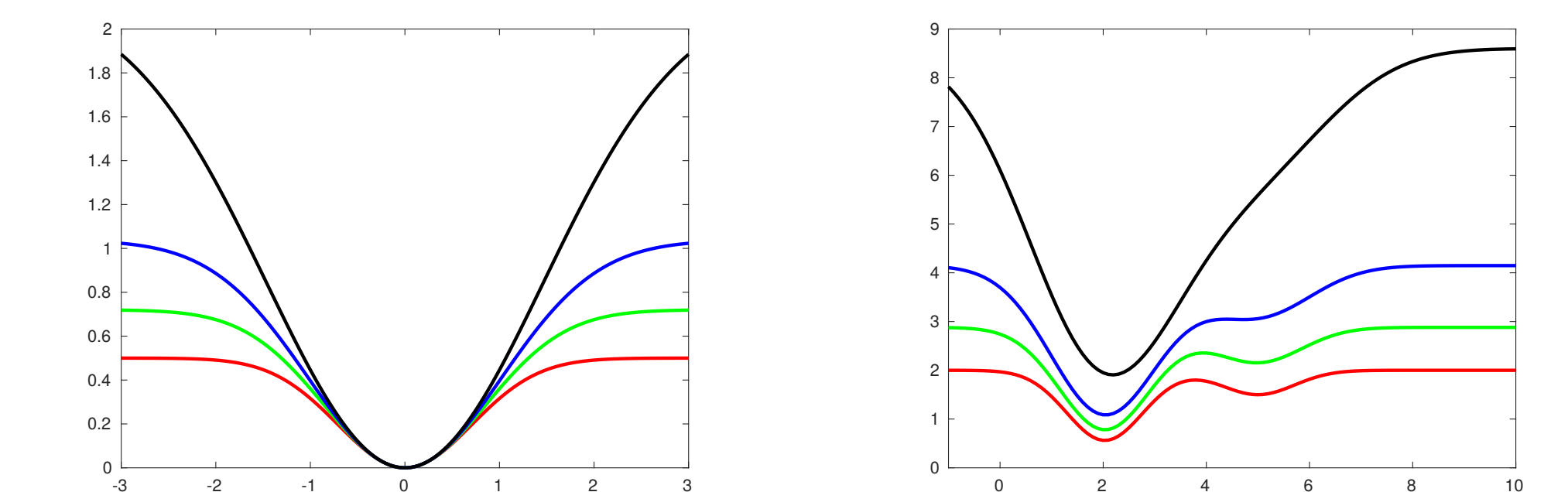
[1] Christopher Zach. Robust bundle adjustment revisited. ECCV 2014.

## 4) Graduated optimization

1. Build a sequence of objectives  $(\Psi^0, \dots, \Psi^{k_{\text{max}}})$  s.t.  $\Psi^0 = \Psi$  and  $\Psi^{k+1}$  is "easier" to optimize than  $\Psi^k$

Natural approach:  $(s_k)_{k=0}^{k_{\text{max}}}$  s.t.  $s_0 = 1$  and  $s_k < s_{k+1}$ ,

$$\Psi^k(\theta) := \sum_i \psi^k(\|\mathbf{f}_i(\theta)\|) \quad \text{with} \quad \psi^k(r) := s_k^2 \psi(r/s_k)$$



Sequence of smoothed kernels ( $\psi^k$ )

Sequence of objectives ( $\Psi^k$ )

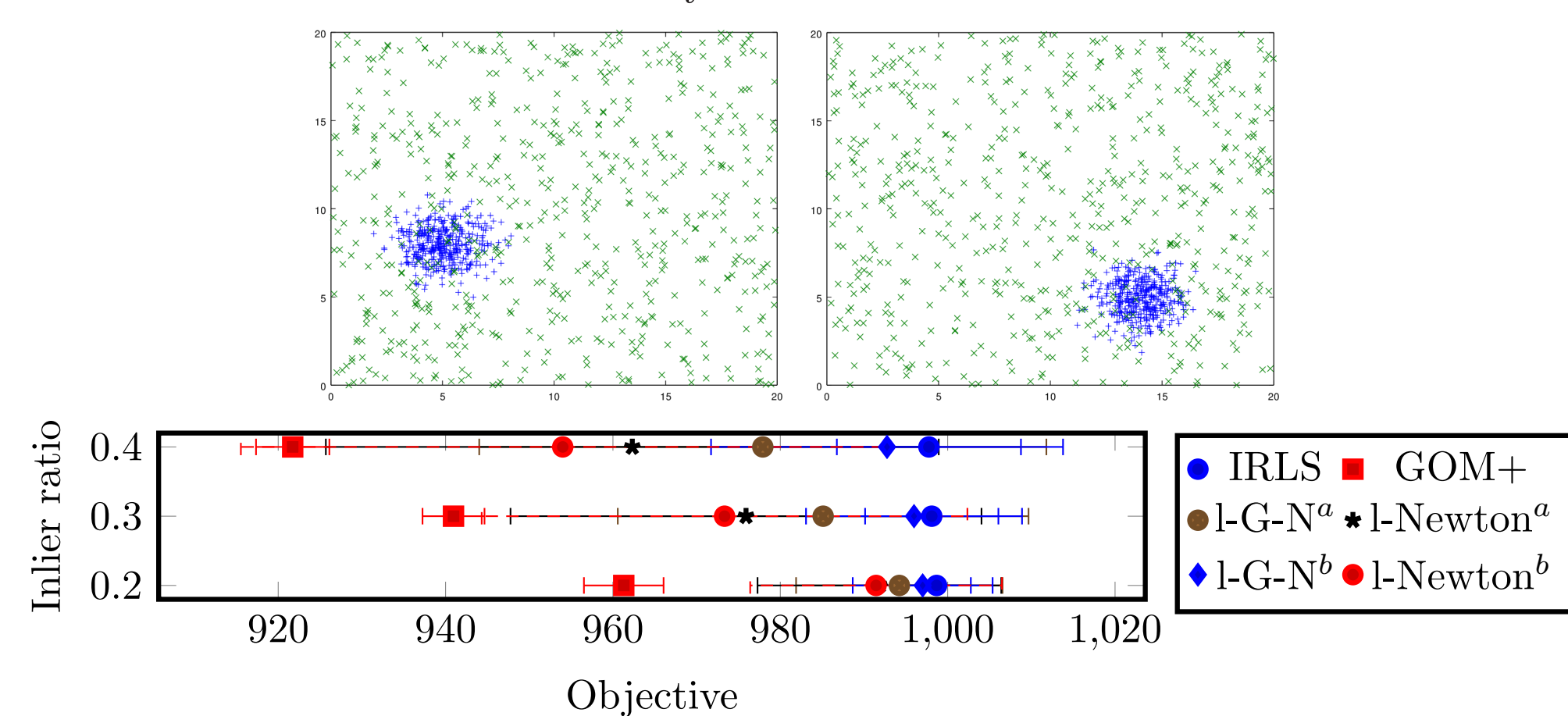
2. Successively optimize the sequence of cost functions using for instance a direct solver

**Our contribution** A novel stopping criterion to speed-up graduated optimization methods.

## 5) Results

### Robust mean

$$\min_{\theta} \sum_i \psi(\|\theta - y_i\|)$$



Average objective (and standard deviation) reached by the different methods for the "robust mean" problem

### Image smoothing

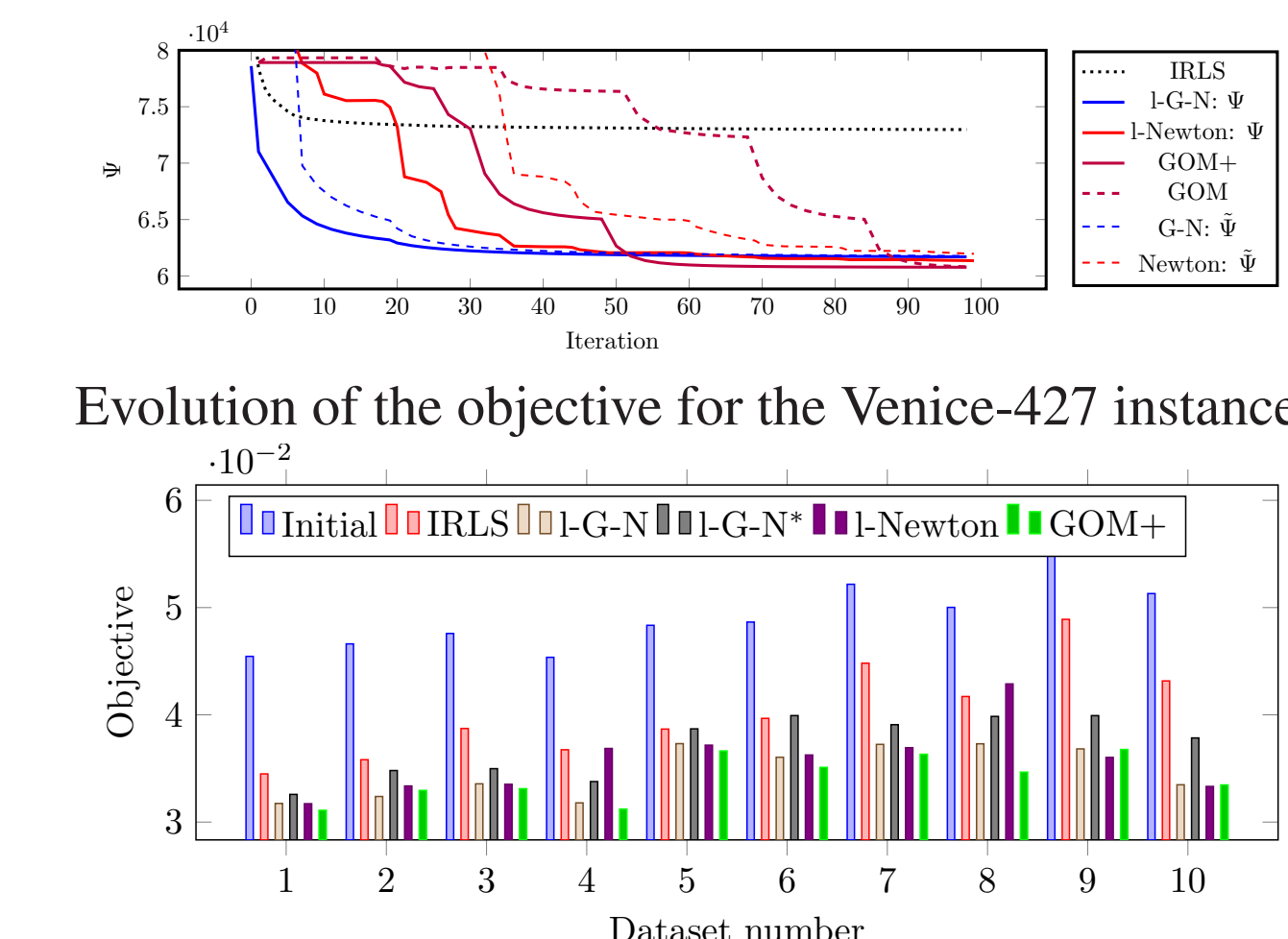
$$\min_{\theta} \sum_{i \in V} \psi^{\text{data}}(\theta_i - u_i) + \sum_{(i,j) \in E} \psi^{\text{smooth}}(\theta_i - \theta_j)$$



Visual results for the "image smoothing" problem using random init

### Bundle adjustment

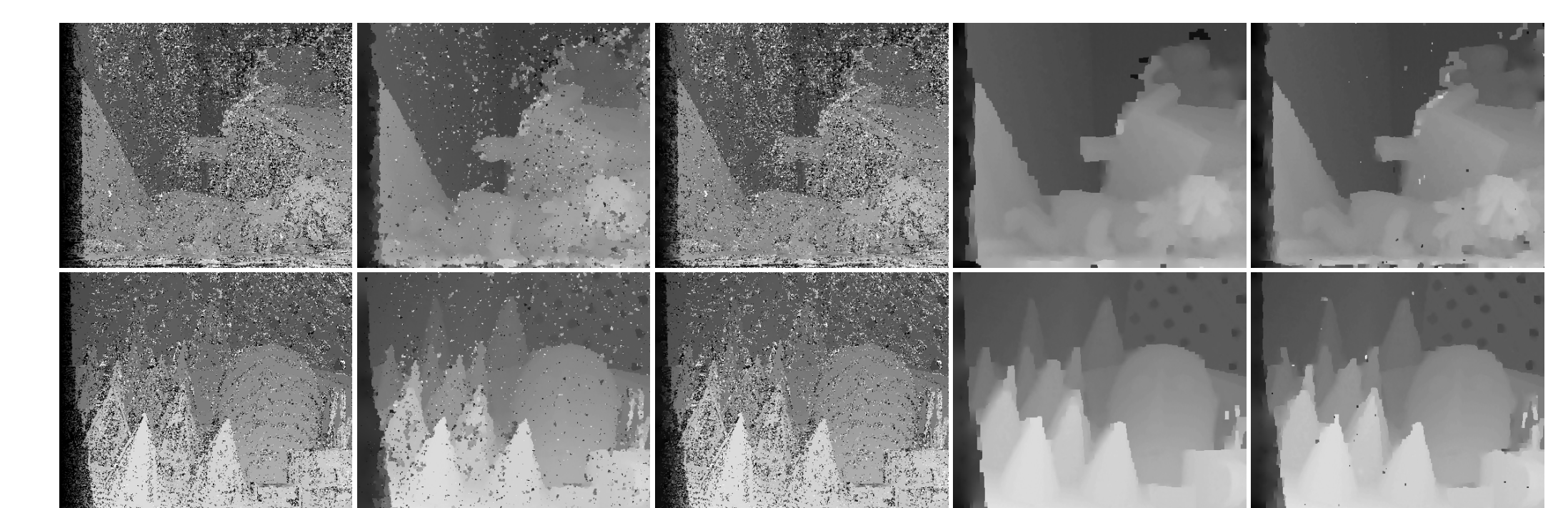
$$\min_{\{\mathbf{R}_i, \mathbf{t}_i\}_i, \{\mathbf{X}_j\}_j} \sum_{i,j} \psi(\|\pi(\mathbf{R}_i \mathbf{X}_j + \mathbf{t}_i) - \mathbf{q}_{ij}\|)$$



Objective values reached by the different methods for metric BA

### Dense stereo

$$\min_{\theta} \frac{\lambda}{2} \sum_{i \in V} \sum_{k=1}^K \psi^{\text{data}}(\theta_i - d_{i,k}) + \sum_{(i,j) \in E} \psi^{\text{smooth}}(\theta_i - \theta_j)$$



Local stereo I-G-N (K = 1) I-G-N (K = 5) GOM+ (K = 1) GOM+ (K = 5)

Visual results for the "variational stereo" problem using random init