Point descriptors. Right column: Sparse-to-dense feature

matching using hypercolumns. Both correspondences are

displayed after applying a ratio test. Our approach tends to

provide a lot more matches, which are overall more robust

thanks to the hypercolumn descriptors.



Figure 2: **Correlation maps visualization.** Left column: Retrieved database image with a reprojected 3D point from the local point cloud. Middle column: Correlation map obtained for the sparse descriptor. Right column: Query image. The bottom-three triplets show cases where matching is ambiguous. Such cases are usually dismissed thanks to the ratio test.

159

160 161 213

214

215



Figure 3: **Inlier correspondences obtained using RANSAC+PnP.** We show correspondences obtained with our 'Sparse-to-Dense Hypercolumn Matching' method, on difficult vegetation scenes from Extended CMU Seasons. The bottow row shows failure cases due to a failed global image retrieval.

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